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APPLICATION FOR LETTERS PATENT

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TITLE: *Int* *A* IMAGE PICKUP APPARATUS AND IMAGE PICKUP
METHOD

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SPECIFICATION

TITLE OF THE INVENTION

IMAGE PICKUP APPARATUS AND IMAGE PICKUP METHOD

BACKGROUND OF THE INVENTION

[Technical Field]

The present invention relates to an image pickup apparatus. More particularly, the present invention relates to an image pickup apparatus which is applied to a video camera using a complementary mosaic color coding CCD.

[Prior Art]

A single-board CCD color camera system or the like captures color images by using a single solid-state image pickup element such as a CCD image sensor. Such a system needs to provide each pixel with a different color filter namely a color coding filter on the CCD image sensor as an image pickup element.

FIG. 1 shows an example of a color array structure used for the complementary mosaic color coding filter as an example of a color coding filter. In this figure, Cy stands for cyan, Ye for yellow, G for green, and Mg for magenta. There are lines N0 to N5. The i th line is indicated as N_i ($0 \leq i$). Each pixel is expressed as the j th pixel ($0 \leq j$). According to this convention, X_{ij} means color X for the j th pixel on line N_i . For example, G_{12} means color G (green) for the second pixel on line N_1 . An example in FIG. 3 shows that colors are repeated horizontally at a 2-pixel interval such as Cy, Ye, Cy, Ye, and so on. Colors are repeated vertically at a 4-pixel (4-line) interval such

as Cy, G, Cy, Mg, and so on. Namely, this example uses a 2-pixel interval for horizontal repetition and a 4-line interval for vertical repetition.

FIG. 2 is a block diagram of a camera signal processing system for a video camera apparatus as an image pickup apparatus. This system is provided with a CCD image sensor 102 which uses such a complementary mosaic color coding filter as illustrated in FIG. 1 or 3.

In FIG. 2, an image pickup signal from an optical system 101 is sensed in a CCD image sensor 102 and is sent to a delay circuit 120 via a front end circuit 103. The optical system 101 comprises a camera lens, a mechanical shutter, and the like. The CCD image sensor 102 functions as an image pickup element. The front end circuit 103 comprises a CDS (correlation double sampling) circuit, a GCA (gain control amplifier), an A/D (analog/digital) converter, and the like. The CCD image sensor 102 is supplied with a pulse signal read from a timing generator 106. The front end circuit 103 is supplied with a sampling pulse, an A/D converter drive pulse, and the like from the timing generator 106. The timing generator 106 is supplied with a control signal from a system control circuit 107. The delay circuit 120 is also supplied with a control signal from the system control circuit 107. An output signal from the delay circuit 120 is sent to a Y (brightness) process circuit 140 and a C (chromaticness) process circuit 160 via a preprocessing circuit 130. The Y process circuit 140 and the C process circuit 160 are also provided with a control signal from the system control circuit 107.

(1,0,3)/(3,0,1) for a filter operation. With respect to a signal for lines N2+N3 in FIG. 4, a filter operation using tap factors (1,0,3) signifies multiplying Cy20+Mg30 by the weight 1 and multiplying Cy22+Mg32 by the weight 3. (Additionally, there may be normalization through the use of division by a sum of factors.) Such a filter operation synchronizes horizontal spatial phases.

During the chromaticness signal processing in FIG. 5, delay lines of the delay circuit 120 synchronize vertical spatial phases for the signal [HH1D] and the signal ([HH0D]+[HH2D])/2. The horizontal spatial phase synchronization filter 161 synchronizes a horizontal spatial phase for each of these signals as S1 and S2. The postprocessing circuit 162 generates a chromaticness signal by processing signals S1r, S2r, S1b, and S2b whose vertical and horizontal spatial phases are synchronized.

The above-mentioned signals [HH1D] and ([HH0D]+[HH2D])/2 are expressed as follows with regard to pixel rates for the CCD image sensor 102.

$$[HH1D]=N2+N3$$

$$([HH0D]+[HH2D])/2 = ((N0+N1)+(N4+N5))/2$$

A chromaticness signal is created at the CCD pixel rate based on data for six lines N0 to N5 in a vertical direction. Namely, the following filter operation is performed in a vertical direction according to filter tap factors.

$$(0,0,2,2,0,0)/(1,1,0,0,1,1)$$

A camera signal processing system according to the conventional field reading causes a problem during chromaticness processing. Specifically, given that "fsv"

alternate repetition of Mg and G. The complementary mosaic color coding filter is based on a repetition of two pixels horizontally by four lines vertically.

The spatial phase synchronization means generates a signal whose horizontal and vertical phases are synchronized. The synthesis means performs the following operations based on Cy (cyan), Ye (yellow), G (green), and Mg (magenta) in each pixel data for that signal.

$$S1r = Cy + G, S2r = Ye + Mg$$

$$S1b = Cy + Mg, S2b = Ye + G$$

These operations create new signals S1r, S2r, S1b, and S2b.

An image pickup apparatus according to the present invention comprises: an image pickup element having a color coding filter; spatial phase synchronization means for synchronizing horizontal and vertical spatial phases based on output from each line in the image pickup element; and synthesis means for generating a synthesized signal based on a signal from the spatial phase synchronization means, wherein this signal has a spatial phase synchronized horizontally and vertically. The image pickup apparatus according to the present invention can eliminate a false signal at (1/4) fsv in a chromaticness signal and greatly improve images by processing chromaticness of signals from this synthesis means.

BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWINGS

FIG. 1 shows an example of a complementary mosaic color coding filter on a CCD image sensor;

FIG. 2 is a block diagram showing an example of a camera signal processing system for a conventional video camera apparatus;

FIG. 3 illustrates 2-line mixed reading for the CCD image sensor;

FIG. 4 illustrates a CCD output signal generated by 2-line mixed reading of the CCD image sensor;

FIG. 5 is a block diagram showing part of a configuration associated with the conventional chromaticness signal processing;

FIG. 6 is a block diagram showing a configuration of a video camera apparatus to which an embodiment of the present invention is applied;

FIG. 7 is a block diagram showing part of a configuration associated with the chromaticness signal processing which is a major function for an embodiment of the present invention;

FIG. 8 illustrates frame reading on the CCD image sensor;

FIG. 9 illustrates a CCD output signal when two field signals are used to read all pixels from the CCD image sensor by interlaced scanning; and

FIG. 10 illustrates a signal after rearrangement according to a pixel array on the CCD image sensor with reference to the CCD output signaling FIG. 9.

DETAILED DESCRIPTION OF THE INVENTION

Embodiments of an image pickup apparatus according to the present invention will be described in detail, with reference to the accompanying drawings. FIG. 6 is a block diagram showing a system configuration of a video camera apparatus as the

embodiment of an image pickup apparatus according to the present invention. FIG. 7 is a block diagram showing part of a configuration associated with the chromaticness signal processing which is a major function for the embodiment of the present invention.

In FIG. 6, an optical system 11 in a camera comprises a lens, a mechanical shutter, and the like. A CCD image sensor 12, functioning as an image pickup element, picks up and photoelectrically converts an optical image from the optical system 11. The CCD image sensor 12 can read all pixels. More specifically, all pixels are read on a frame basis in an interlaced scanning CCD. The interlaced scanning and frame reading generates a 2-field signal. This signal corresponds to an image which is exposed at the same time by the mechanical shutter in the optical system 11.

An image pickup signal generated from the CCD image sensor 12 is supplied to a front end circuit 13. The front end circuit 13 comprises a CDS (correlation double sampling) circuit, a GCA (gain control amplifier), an A/D (analog/digital) converter, and the like for detecting each pixel's electric charge which is photoelectrically converted and stored in the CCD. An output signal from the front end circuit 13 is sent to a delay circuit 20 via a memory control circuit 14. Memory 15 is connected to the memory control circuit 14. The memory 15 is used for rearranging the frame-read signal from the CCD image sensor 12 according to spatial array data on the CCD.

The CCD image sensor 12 is supplied with a read pulse signal from a timing

generator 16. The front end circuit 13 is supplied with a sampling pulse, an A/D converter drive pulse, and the like from the timing generator 16. The timing generator 16 is supplied with a control signal from a system control circuit 17. A delay circuit 120 is also supplied with a control signal from the system control circuit 17.

The following describes the frame read operation from the CCD image sensor 12 and the rearrangement in the memory 15 with reference to FIGS. 8 to 10. FIG. 8 illustrates frame reading on the CCD image sensor 12. This operation reads all pixels on all lines N0 to N5. Since interlaced scanning is performed every other line, a CCD output signal is read as a 2-field signal as shown in FIG. 9. This signal comprises a first field F1 for even-numbered lines N0, N2, and N4, and a second field F2 for odd-numbered lines N1, N3, and N5. The memory control circuit 14 controls to write or read a signal for two fields F1 and F2 from memory 15. As shown in FIG. 10, this signal is arranged for output in the order of spatial arrays on the CCD. The output signal from the memory control circuit 14 in FIG. 10 becomes a frame image signal which follows the order of lines N0 to N5 on the CCD.

Again in FIG. 6, an output signal from the delay circuit 20 is sent to a Y (brightness) process circuit 40 and a C (chromaticness) process circuit 60 via a preprocessing circuit 30. A control signal from the system control circuit 17 is also supplied to the Y process circuit 40 and the C process circuit 60.

FIG. 7 shows part of a configuration associated with the chromaticness signal processing which is a major function for the embodiment of the present invention. In

this FIG. 7, the delay circuit 20 retrieves a no-delay signal [H0D] and 1H delay signal [H1D] to 5H delay signal [H5D], and sends these signals to a preprocessing circuit 30 using five 1H (one horizontal interval or one line) delay devices 21 to 25. With regard to correspondence among these signals [H0D] to [H5D] and lines N0 to N5 in FIG. 10, for example, the no-delay signal [H0D] corresponds to line N5. The 1H delay signal [H1D], the 2H delay signal [H2D], ... and the 5H delay signal [H5D] correspond to the line N4, the line N3, ... and the line N0, respectively.

In the preprocessing circuit 30, the signals [H0D] to [H5D] are added as follows. An adder 31 adds signals [H0D] to [H1D]. An adder 32 adds signals [H2D] to [H3D]. An adder 33 adds signals [H4D] to [H5D]. An adder 34 adds output from the adder 31 to output from the adder 33. A 1/2 multiplier 35 halves output from the adder 34. The preprocessing circuit 30 sends an output signal $([H0D]+[H1D]+[H4D]+[H5D])/2$ from the multiplier 35 and an output signal $([H2D]+[H3D])$ from the adder 32 to a Y process circuit 40. An output signal $([H2D]+[H3D])$ from the adder 32 is to be processed currently. The signals [H0D] to [H5D] are sent to a synthesizer circuit 38 via a horizontal spatial phase synchronization filter 36 and a vertical spatial phase synchronization filter 37. Signals S1r/S2r and S1b/S2b from the synthesizer circuit 38 are sent to a C process circuit 60. The horizontal spatial phase synchronization filter 36 uses the following tap factors for filter operations.

$$(1,0,3)/(3,0,1)$$

to find data (pixel values) for these complementary colors Cy, Ye, Mg, and G instead of these pixels Cy22, Ye23, Mg32, and G33.

In order to explain the example, it is assumed that Vp is a vertical spatial phase and Hp is a horizontal spatial phase of the point p for synchronizing the spatial phases. Each pixel has a subscript such as say "23" in Ye23. In this example, "2" represents a vertical phase and "3" represents a horizontal phase. Each pixel data at the point p can be expressed as CyVpHp, YeVpHp, MgVpHp, and GVpHp. The example in FIG. 10 assumes Vp=2.5 and Hp=2.5. As an example, the following describes how to find CyVpHp using an interpolation or filter operation. In this case, the horizontal spatial phase synchronization filter 36 is first used to find pixel data Cy0Hp, Cy2Hp, and Cy4Hp having the horizontal phase Hp=2.5. These pixel data can be found by performing the following filter operations using tap factors (3, 0, 1).

$$\text{Cy0Hp} = 3*\text{Cy02} + 0*\text{Ye03} + 1*\text{Cy04}$$

$$\text{Cy2Hp} = 3*\text{Cy22} + 0*\text{Ye23} + 1*\text{Cy24}$$

$$\text{Cy4Hp} = 3*\text{Cy42} + 0*\text{Ye43} + 1*\text{Cy44}$$

Generally, operations with tap factor 0 are omitted as follows.

$$\text{Cy0Hp} = 3*\text{Cy02} + 1*\text{Cy04}$$

$$\text{Cy2Hp} = 3*\text{Cy22} + 1*\text{Cy24}$$

$$\text{Cy4Hp} = 3*\text{Cy42} + 1*\text{Cy44}$$

The same applies to the following description. The horizontal spatial phase synchronization filter 36 uses the same tap factors (3, 0, 1) for Mg. However, tap

factors (1, 0, 3) are used for Ye and G.

As mentioned above, the horizontal spatial phase synchronization filter 36 synchronizes horizontal spatial phases in pixel data such as Cy0Hp, Cy2Hp, and Cy4Hp.

This pixel data is sent to the vertical spatial phase synchronization filter 37 which then synchronizes vertical spatial phases in the pixel data.

The following filter operation uses tap factors (1, 0, 4, 0, 3, 0) to find pixel data having the vertical phase $V_p=2.5$ such as CyVpHp.

$$CyVpHp = 1 * Cy0Hp + 4 * Cy2Hp + 3 * Cy4Hp$$

The tap factors (1, 0, 4, 0, 3, 0) are used for finding YeVpHp. However, the tap factors (0, 3, 0, 4, 0, 1) are used for finding MgVpHp and GVpHp.

As mentioned above, horizontal and vertical spatial phases are synchronized for pixel data CyVpHp, YeVpHp, MgVpHp, and GVpHp. The synthesizer circuit 38 then performs the following operations using data for these complementary colors Cy, Ye, Mg, and G of the pixel data.

$$S1r = Cy + G, S2r = Ye + Mg$$

$$S1b = Cy + Mg, S2b = Ye + G$$

These operations create signals S1r, S2r, S1b, and S2b. These signals are sent to the postprocessing circuit 62 in the C process circuit 60.

Signals S1r, S2r, S1b, and S2b from the synthesizer circuit 38 are created according to an array of 2 x 2 pixels on the CCD. Given that "fsv" signifies a sampling

frequency in the vertical direction, no false color occurs at $(1/4)$ fsv.

The present invention is not limited to the above-mentioned embodiment. While the embodiment describes an application to the video camera apparatus, the present invention can be applied to other image pickup apparatuses. While the embodiment explains signal processing by means of a frame read operation using the interlaced scanning CCD, the present invention can be applied to a system which can read data for each discrete line in a complementary mosaic color coding CCD. The pixel array for complementary mosaic color coding is not limited to the embodiment. Other arrays are also available. The present invention can be applied to the use of a color coding filter for three primary colors. It is further understood by those skilled in the art that various changes and modifications may be made in the invention without departing from the spirit and scope thereof.